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# Rheology of model lipid layer to understand biolubrication

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Nature has produced water-based lubrication systems that outclass by far the best of man-made devices [1]. Biological contacts such as the articulating cartilage surfaces in human hips or knees often operate under severe conditions (i.e., high load and low speed), corresponding to the boundary lubrication regime. In this regime, direct contact between the surfaces can be prevented by a boundary lubricant of nanometer range thickness that attaches to the solid surfaces, thereby reducing drastically the friction coefficient down to  $\mu=0.005-0.02$  for the human joint. Phospholipid layers are well controlled model systems that mimic boundary biolubrication (Fig. 1).

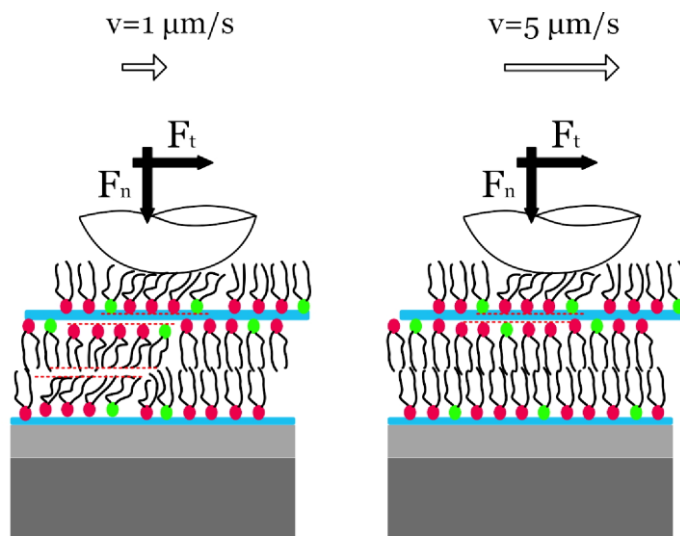


Figure 1: Schematic representation of a phospholipid trilayer sheared between a rigid spherical indenter and a flat plate for which localization of the sliding plane at low and high velocities will be performed.

The present PhD project aims to better understand the role of these phospholipid layers in biolubrication. We have developed an original experimental set-up [2], coupling the precise tribological characterization of the system with the measurement of velocimetry by Fluorescence Recovery After Patterned Photobleaching. By associating velocimetry and tribology experiments on well controlled model systems, it will give us the unique opportunity to address the question of the localization of the sliding plane. The work in this project will focus on three major axes: (i) to adapt the experimental set-up to work with controlled humidity or fully hydrated samples; (ii) to analyze the influence on lubrication properties; (iii) to compare the experimental results with simulations based on Molecular Dynamics (collaboration with C. Loison, ILPM, LYON).

The candidate should be a physicist with a strong background in soft condensed matter and material sciences. The project is mainly experimental, but modelisation and numerical simulations aspects will also be important.

[1] M. Urbakh, J. Klafter, D. Gourdon, and J. Israelachvili, *Nature*, **430**, 525–528 (2004).

[2] L. Fu, D. Favier, T. Charitat, C. Gauthier, and A. Rubin, *Rev. of Sci. Instrum.* **87**, 033903 (2016).